

# Mechanical controls on the deformation of continents at convergent margins

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## Abstract

Spatial variations in the rigidity of continental plates (expressed in terms of an effective elastic thickness,  $T_e$ ) can have a profound influence on the style of deformation of ocean–continent convergent margins. Depending on the spatial distribution of  $T_e$ , strains related to plate boundary forces can become concentrated where  $T_e$  is small. We calculate  $T_e$  and  $T_e$  anisotropy in western Canada by using and comparing the wavelet and multitaper coherence methods. In addition to a nearly stepwise change in  $T_e$  from the Cordillera to the craton, we show that weak axes of  $T_e$  anisotropy are parallel with most compressive directions of horizontal stress components and fast axes of upper mantle seismic anisotropy. Maxima in the magnitude of  $T_e$  anisotropy are spatially correlated with the locations of most earthquakes and the locations and directions of maxima in electrical anisotropy and conductivity. The pattern of brittle failure and seismicity is explained as a response to plate boundary forces acting on a plate of variable rigidity and is expected to induce the observed mechanical anisotropy and enhance the flow of crustal fluids, resulting in locally high electrical conductivities. Our combined results thus suggest for the first time that the elastic properties of continental lithosphere have a leading order influence on the deformation and evolution of convergent plate boundaries.

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## 1. Introduction

At a continental convergent boundary long-term tectonic loading may deform a lithospheric plate permanently by two mechanisms: brittle failure in the cool upper part of the lithosphere and by effectively viscous flow in the hotter deeper regions. The maximum stress that can be supported by the lithosphere is thought to occur at the intersection of these regimes, the so-called brittle–ductile transition (Kohlstedt et al., 1995). Under a

present-day stress regime brittle failure is apparent from seismicity. A number of studies have shown that the depth to which seismicity occurs (the seismogenic zone) plausibly corresponds to a lower bound to the elastic thickness,  $T_e$ , which for a lithostatic state of stress is the vertical fraction of the lithosphere that behaves elastically over geological time scales (Maggi et al., 2000; Watts and Burov, 2003). The flexural rigidity  $D \propto ET_e^3$ , where  $E$  is Young's modulus, is a rheological property that governs the resistance of the lithosphere to flexure by plate boundary forces (Watts, 2001). The strong dependence of  $D$  on  $T_e$  implies that the magnitude and spatial variations of  $T_e$  can have a significant influence on the degree and

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style of deformation due to long-term tectonic loads. In particular, it is expected that spatial variations in  $T_e$  can prescribe where stress concentration may occur and consequently determine the location of earthquakes, as well as mechanical anisotropy, due to the localized brittle failure of crustal rocks (Lowry and Smith, 1995).

The mechanics governing the tectonic evolution of convergent plate boundaries remain a major focus of both observational (Peacock, 1990; Stern, 2002) and modelling (Becker et al., 1999; Billen et al., 2003; Stegman et al., 2006) studies of subduction zones. However, although potentially important, the influences of  $T_e$  variations on the rheology, dynamics and evolution of convergent margins are poorly understood (Burov and Diament, 1995; Gaspar-Escribano et al., 2001). A central reason is the difficulty in constraining spatial variations in  $T_e$ . Only a few studies (e.g. Flück et al., 2003; Rajesh et al., 2003) have focused on estimating  $T_e$  in active convergent tectonic settings using window-based methods. More recently, Tassara et al. (2007) used the wavelet method to calculate  $T_e$  in South America. In this study we calculate  $T_e$  and  $T_e$  anisotropy in western Canada by using and comparing the multitaper and wavelet transform methods. Western Canada is an ideal target for  $T_e$  studies because it has a rich and diverse tectonic history spanning  $\sim 3$  Ga, where rigidity variations may have played a major role in continental evolution. This region encompasses three main tectonic domains: the young and tectonically active Phanerozoic Cordillera to the west, the Paleo-Proterozoic Interior Plains covered by a thick layer of Phanerozoic sediments, and the stable Archean Craton to the east. The tectonic evolution of the plate margin has been dominated by convergence since the Mesozoic (Price, 1986). The plate boundary at the western edge of the continent is currently defined by the subduction of the Juan de Fuca plate to the south, and the strike-slip Queen Charlotte fault system to the north.

To gain a sound understanding of the mechanical controls on the deformation of the lithosphere at convergent margins,  $T_e$  results should be compared with a range of geophysical indicators of lithospheric deformation (Eaton and Jones, 2006). In western Canada several experiments conducted by LITHOPROBE and POLARIS provide a wealth of seismic, magnetotelluric, and heat flow data. In this paper we start by using and comparing the multitaper and wavelet methods for estimating  $T_e$  and  $T_e$  anisotropy. We then compare the results with a range of geophysical observables from the same region. The geophysical correlations allow us to formulate a conceptual model of deformation at convergent margins that can be tested in future studies of lithospheric dynamics.

## 2. $T_e$ estimation

### 2.1. Coherence method

$T_e$  is estimated by minimizing the misfit (L2 norm) between the observed spectral coherence between topography and Bouguer gravity anomalies and the coherence predicted for the flexure of a uniform elastic plate bending under the weights of topography at the surface and internal loads related to density variations (Watts, 2001). The plate response is modelled either as isotropic or anisotropic, and the coherence is inverted for a single parameter,  $T_e$ , or the three parameters of an assumed orthotropic elastic plate (i.e. having different rigidities in two perpendicular directions),  $T_{\min}$ ,  $T_{\max}$ , and  $\phi$ , the direction of weakest rigidity (Swain and Kirby, 2003). The coherence is an averaging property which measures the consistency of the phase dependence between two signals or fields at distinct wavelengths. Applied to topography and gravity data sets, it provides a measure of the degree of flexural compensation of tectonic loads. An important physical parameter for understanding this property is the characteristic flexural wavelength,

$$\lambda_F \sim \left( \frac{ET_e^3}{\Delta\rho g} \right)^{1/4} \quad (1)$$

where  $\Delta\rho$  is the density contrast at the depth of compensation,  $g$  is the gravitational acceleration, and “ $\sim$ ” means “scales as”. At short wavelengths ( $\lambda \ll \lambda_F$ ) the loads are fully supported by elastic stresses and the Bouguer anomaly is not coherent with the topography. In contrast, at long wavelengths ( $\lambda \gg \lambda_F$ ) loads are compensated isostatically and the Bouguer anomaly is coherent with topography. Typical coherence curves vary smoothly from 0 to 1, reflecting the transition from flexurally-supported to fully compensated loads. In particular, Eq. (1) indicates that the wavelength of transition from compensated to uncompensated loads increases for increasing plate rigidity.

In the continents the elastic thickness estimated using the coherence method ranges between very low ( $T_e < 10$  km) and very high ( $T_e > 100$  km) values, reflecting the wide variety of tectonic settings and the thermal evolution of the lithosphere (Pérez-Gussinyé et al., 2004). Discrepancies occur, however, when the results from different spectral estimation and load deconvolution techniques applied to the same datasets are compared (Pérez-Gussinyé et al., 2004; Audet and Mareschal, 2007). This problem arises because  $T_e$  is a wavelength dependent parameter (Eq. (1)), and the accuracy of its estimation is controlled by the

spatio-spectral resolution of the analysis technique. Window-based methods have good resolution in frequency, but lack spatial resolution, depending on window width. Spatio-spectral (or space-scale) methods, on the other hand, offer a compromise on the resolution in both reciprocal domains, and are thus able to characterize spatial discontinuities. It is thus important to use and compare different spectral methods whenever possible.

In contrast to most previous analyses of  $T_e$ , generally relying on a single spectral technique (e.g. Lowry and Smith, 1995; Simons et al., 2000; Kirby and Swain, 2006; Audet and Mareschal, 2007), we maximize both spatial and wavelength resolutions by using and comparing two spectral techniques for the calculation of the coherence and the estimation of  $T_e$ : the multitaper (Simons et al., 2000; Pérez-Gussinyé et al., 2004) and wavelet transform (Kirby and Swain, 2006; Audet and Mareschal, 2007) methods. Applied to western Canada, we show that both techniques recover the spatial pattern of  $T_e$  and the  $T_e$  anisotropy, but the wavelet method provides both better spatial resolution and higher absolute estimates of  $T_e$ .

In the inversion, the predicted coherence is calculated by deconvolving the topography and Bouguer anomaly into surface and internal components of the initial loading structure (Forsyth, 1985). See Pérez-Gussinyé et al. (2004) for the details of this calculation. This step requires information on the crustal structure (Moho depth and density contrasts) that we extract from the LITH5.0 crustal model (Perry et al., 2002). We take the subsurface load to be the density contrast at the Moho (Watts, 2001).

The flexural rigidity is converted to  $T_e$  using a Poisson ratio of 0.25 and Young modulus of 100 GPa. Resolution tests and statistical analysis of estimated  $T_e$  values from synthetic modelling show that the accuracy of recovered  $T_e$  strongly depends on the size of the window compared to the flexural wavelength (Audet and Mareschal, 2007), which is expected from Eq. (1). A reasonable estimate of the accuracy of  $T_e$  estimated from spectral methods is  $\pm 15\%$  of the recovered value. Moreover, as  $T_e$  is sensitive to a range of parameters (Burov and Diamant, 1995; Lowry and Smith, 1995), additional uncertainties in the choice of material parameters and modelling approaches can be described as log-normal and of the order 30%–50% (Lowry and Smith, 1995). Since only major trends are of interest, the variance of  $T_e$  estimates will not affect the interpretation of the results.

## 2.2. Multitaper analysis

The multitaper analysis is performed using a set of orthogonal basis functions that minimize the variational problem of broadband bias reduction as data tapers

(Thomson, 1982), such that multiple estimates of the same spectrum are approximately uncorrelated and can be averaged to reduce the estimation variance. The set of functions is characterized by two numbers: the time-frequency bandwidth product  $NW$  that controls the wavelength resolution and spectral leakage, and the number of significant tapers  $k$  that governs the estimation variance. The multitaper spectral estimates are calculated using Discrete Prolate Spheroidal Slepian (DPSS) tapers with  $NW=3$  and  $k=3$  throughout this study. See Pérez-Gussinyé et al. (2004) for the description of the general application of the multitaper method in  $T_e$  studies.

In the multitaper method, the load deconvolution is done in a given rectangular window of the study area and the estimated  $T_e$  value is assigned to the area covered by the window (Pérez-Gussinyé et al., 2004). Spatial resolution is achieved by moving the windows over the entire data set with some overlap. The size  $d$  of the data windows is critical in the estimation of  $T_e$  because small windows provide high spatial resolution but cannot resolve long flexural wavelengths (c.f. Eq. (1),  $d < \lambda_F$ ), while large windows (i.e.  $d \gg \lambda_F$ ) provide an average of the true distribution of  $T_e$  within the window, thus degrading the spatial resolution. Although a popular method (Pérez-Gussinyé et al., 2004), two important limitations of the multitaper method for  $T_e$  estimation emerge because of the trade-off between window size and frequency resolution and cause: (1) limited spatial and wavelength resolution, and (2) lower estimates of  $T_e$ . To counter these effects, we map out results using a combination of window sizes of  $300 \times 300 \text{ km}^2$ ,  $500 \times 500 \text{ km}^2$ , and  $800 \times 800 \text{ km}^2$  (shown at lower left corner of Fig. 3a), with an overlap of 70% between adjacent windows. When the misfit does not converge, we assign a value of 60 km to the window, which is the largest resolvable  $T_e$  value using the  $800 \times 800 \text{ km}^2$  window. Results are extrapolated to the edges of the study area and the maps are averaged. The spatial recovery of  $T_e$  is limited by the size of the smallest window and is restricted to a  $1484 \times 1484 \text{ km}^2$  square region in the center of the study area. Finally, the resulting map is filtered using a Gaussian function of width 140 km to produce a continuous image of  $T_e$  that is more easily comparable to the results obtained with the wavelet transform method. Results do not change for Gaussian functions with different window widths.

The multitaper method also allows for the determination of directional variations of the coherence because the spectra are effectively calculated and averaged at each wavevector ( $k_x$ ,  $k_y$ ) in the 2D spectral plane. The results of the inversion for the anisotropic  $T_e$  cannot be averaged spatially as in the isotropic analysis (above),

because the weak directions can vary between estimates obtained with different window sizes. However the results can be qualitatively compared with those obtained with the wavelet method (below) to assess the general trends seen in the map of  $T_e$  anisotropy.

### 2.3. Wavelet transform

In the wavelet analysis there is no need for fixed spatial window because the wavelet transform, defined

as the convolution of a signal with a scaled and rotated kernel called a wavelet, is a space-scale operation that calculates the spectra at each grid point. The convolution is performed over the entire grid of the study area at different scales, which are related to a Fourier wave-number. In this study we use the directional 2D Morlet wavelet because it is well suited for the study of  $T_e$  and the anisotropy (Kirby and Swain, 2006; Audet and Mareschal, 2007). The Fourier load deconvolution of Forsyth (1985) is performed at each grid point by making

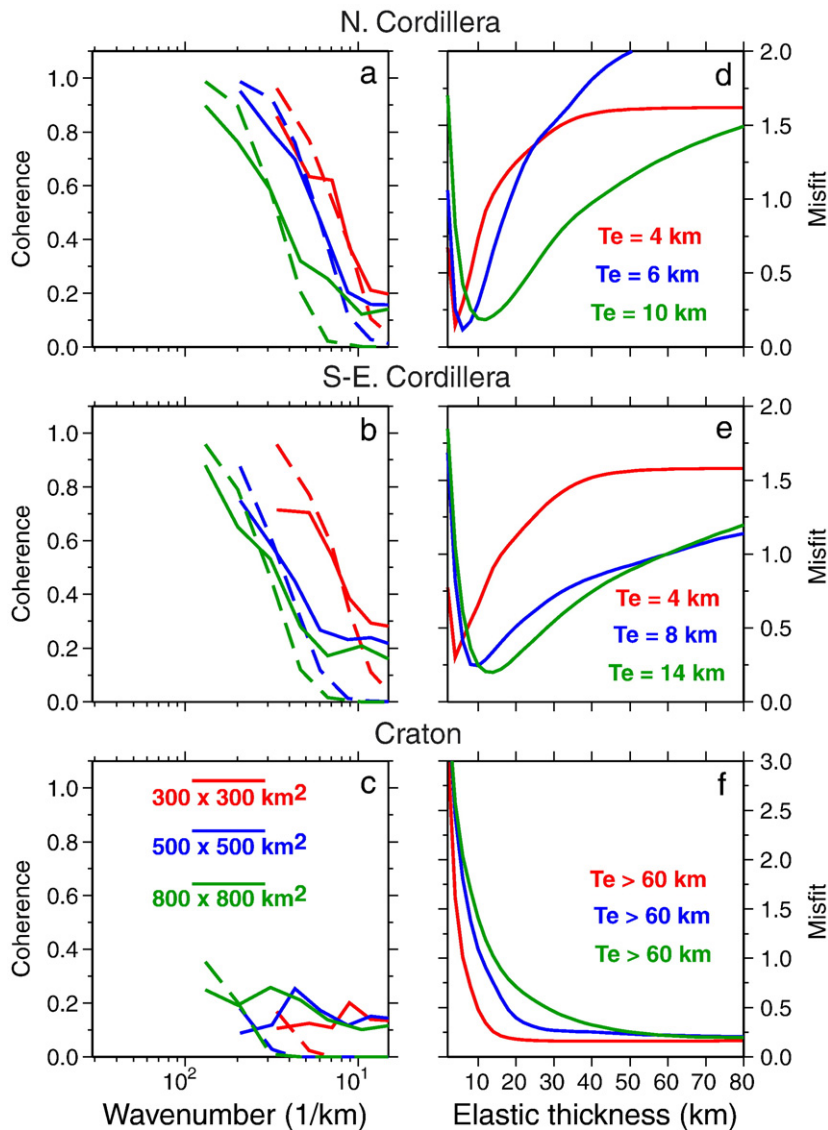


Fig. 1. Examples of  $T_e$  estimated with the multitaper method for the three window sizes: a–c) Observed (solid lines) and predicted (dashed lines) coherence curves for three locations in western Canada ((a) North Cordillera, (b) South-East Cordillera, and (c) Craton); d–f) L2 norm (root mean square) error between observed and predicted coherence curves for a range of  $T_e$  values and for each window used. Sizes of windows are  $300 \times 300 \text{ km}^2$  (red curves),  $500 \times 500 \text{ km}^2$  (blue curves), and  $800 \times 800 \text{ km}^2$  (green curves). (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

the assumption of spatial decoupling between adjacent local wavelet spectra (Stark et al., 2003; Kirby and Swain, 2004; Audet and Mareschal, 2007). In other words, we assume that the wavelet coefficients at one grid point are statistically independent from neighboring coefficients, and apply a Fourier-based deconvolution to the wavelet spectra. In reality, however, spatial and spectral (space-conjugate) resolutions trade-off in the wavelet analysis as implied by the uncertainty principle in information theory, which states that physical and spectral localizations cannot be measured simultaneously with arbitrarily high precision. Short-scale wavelets are well localized in space but broad in the spectral

domain. Large-scale wavelets are well localized in the spectral domain but broad in space. This results in a smoothed version of  $T_e$  where it is large, but allows for larger estimates of  $T_e$  than the multitaper method due to the presence of longer wavelengths contributing to the spectra.

In the anisotropic analysis, the coherence is calculated at distinct azimuths using a directional Morlet wavelet (Kirby and Swain, 2006; Audet and Mareschal, 2007) on a coarse grid for a better visualization of the variations of the weak axes. See Audet and Mareschal (2007) or Kirby and Swain (2006) for the description of the application of the wavelet transform method in  $T_e$  studies.

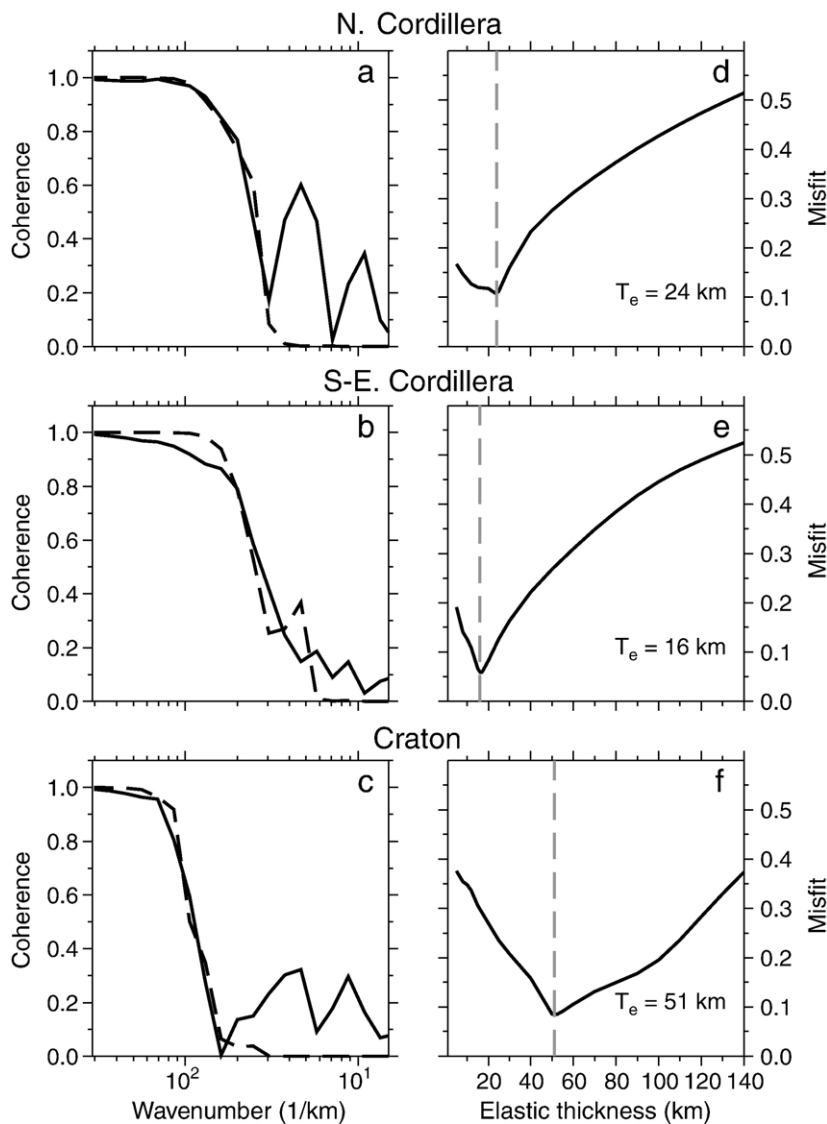


Fig. 2. Examples of  $T_e$  estimated with the wavelet transform method for the three locations indicated on the plots. The coherence curves show the characteristic roll-over from uncompensated (0 coherence) to fully compensated (coherence of 1) loads as well as a clear minimum misfit in all cases.



### 3. Results

#### 3.1. Isotropic $T_e$

Fig. 1 shows example results of the 1D (azimuthally averaged) multitaper coherence for the three window sizes at different locations (N. Cordillera, S-E Cordillera, and Craton). Misfit curves show a clear minimum for small values of  $T_e$  even for the smallest window used. As the size of the window increases, more wavelength information from neighboring regions is retained in the coherence and the estimate can vary by as much as a factor of 5. In the Craton the maximum of the coherence curves remains small even for the largest window size, and the misfits do not converge to a stable  $T_e$  value, indicating that  $T_e$  is large in this region. In comparison, the wavelet coherence shows the characteristic roll-over from uncompensated (0 coherence) to fully compensated (coherence of 1) loads as well as a clear minimum misfit in all cases (Fig. 2).

Multitaper and wavelet maps of  $T_e$  are shown in Fig. 3. Regardless of the technical differences between the two methods, qualitatively, the results agree encour-

agingly well and correlate with major physiographic provinces in western Canada.  $T_e$  varies from <30 km in the Phanerozoic Cordillera to >60 km in the Paleo-Proterozoic Craton over a distance of a few hundred kilometers. This trend is in qualitative agreement with a previous study of  $T_e$  in western Canada that used the maximum entropy spectral estimator (Flück et al., 2003), although the maximum estimates of  $T_e$  in the Craton are generally a factor 2 to 3 smaller.

Despite a good overall qualitative agreement between the  $T_e$  maps, there is a pronounced difference in the Craton where multitaper estimates are lower than 30 km in some instances. The discrepancies stem in part from the ad hoc methodology adopted in Section 2.2 for the mapping of the windowed multitaper estimates, and from the difference in spatial and spectral resolutions between the two methods. In the Craton  $T_e$  is presumably large, such that small windows would not resolve the transition wavelength from low to high coherence. However, high coherence (>0.3, c.f. Fig. 1) at short wavelengths (the “spurious” coherence mentioned in Swain and Kirby (2006) and Audet and Mareschal (2007)) not associated

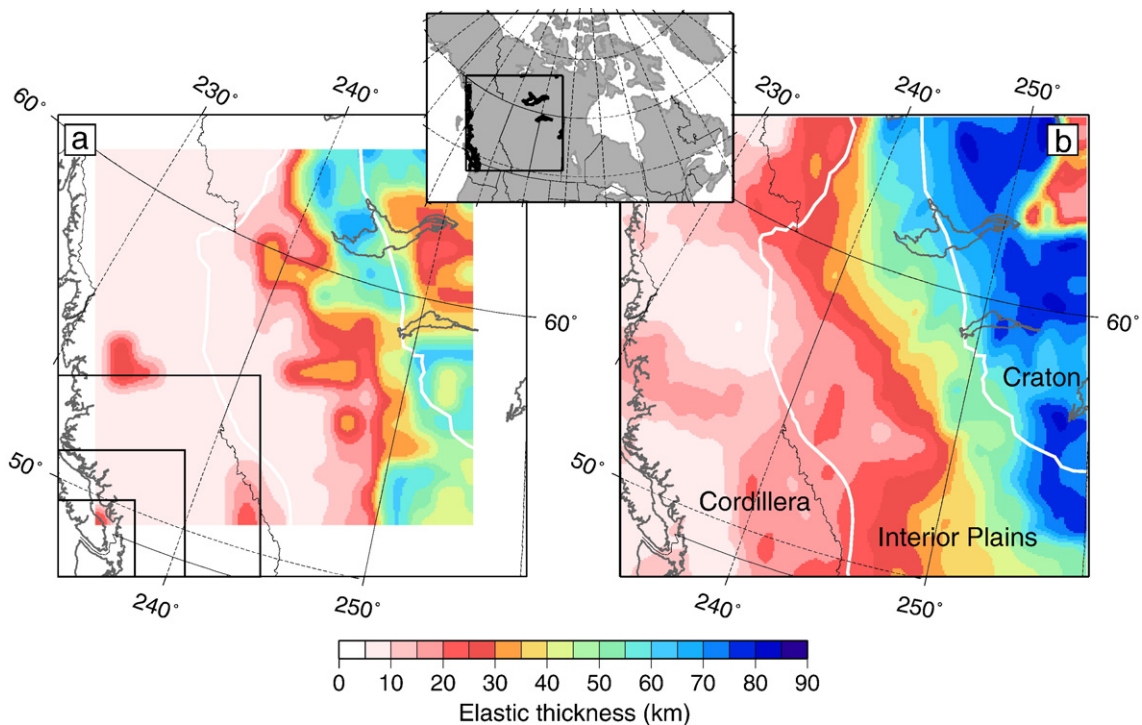


Fig. 3.  $T_e$  structure of western Canada calculated from the coherence between Bouguer gravity and topography using the multitaper (a) and the wavelet transform (b) methods. Data are projected onto a Transverse Mercator grid. Although the values differ in (a) and (b), the qualitative  $T_e$  structure is approximately equivalent, in particular the location of the  $T_e$  gradient. The  $T_e$  results from the multitaper method are lower than those obtained with the wavelet method due to the use of moving windows of different sizes (shown by the boxes at the lower left corner in (a)) which limits the spatial and wavelength resolutions (Simons et al., 2000). Thus, we consider the wavelet results to be more reliable. Major physiographic provinces are bounded by solid white lines. The results show a well-defined transition from low values in the Cordillera, intermediate values in the buried Interior Plains, and high values in the exposed Craton. Inset shows the location of the study area with respect to North America.

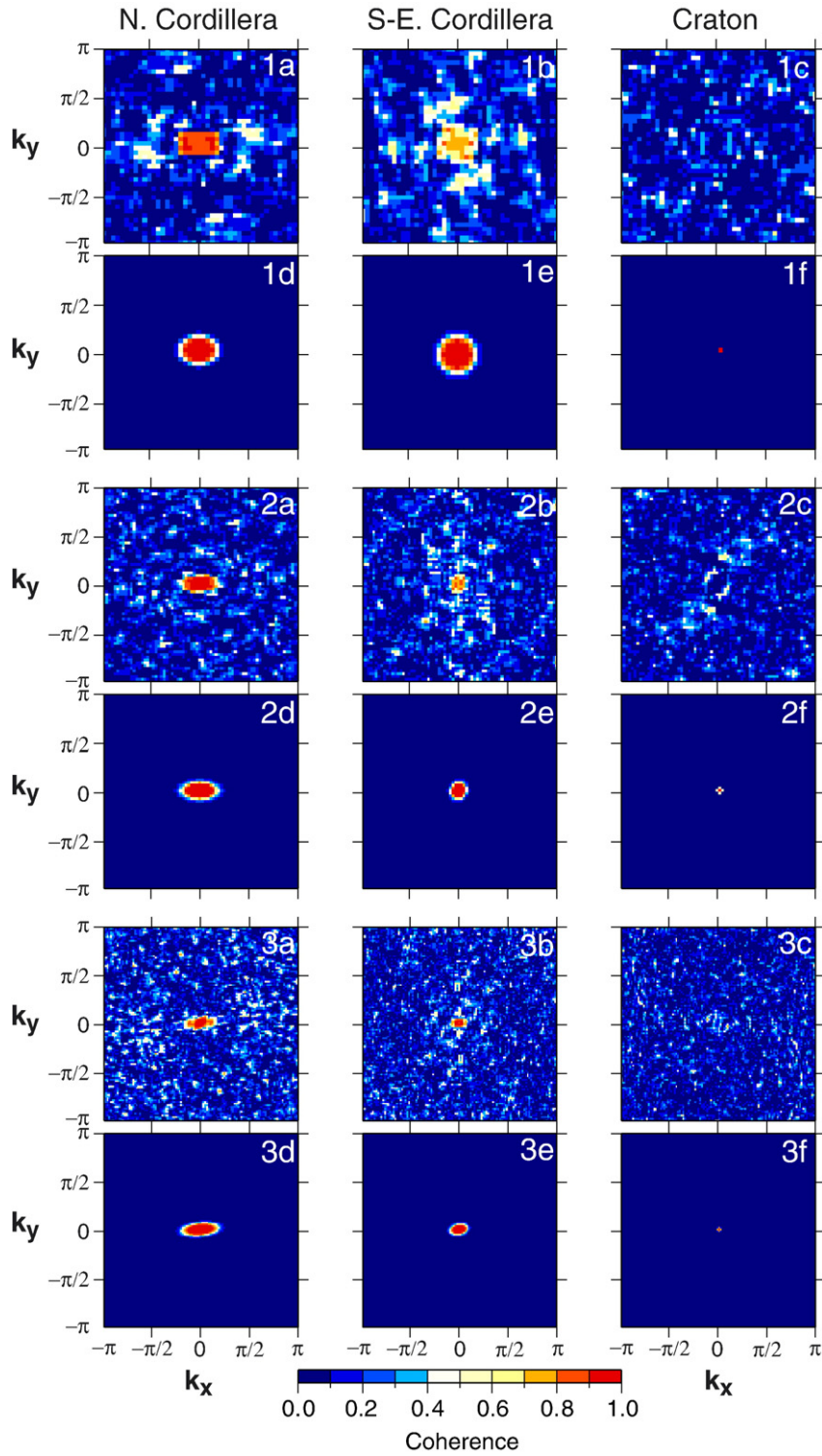


Fig. 4. Anisotropic inversion of  $T_c$  using the multitaper method. Observed (a–c) and theoretical (d–f) 2D coherences using different windows: (1a–f) is  $300 \times 300 \text{ km}^2$ ; (2a–f) is  $500 \times 500 \text{ km}^2$ ; and (3a–f) is  $800 \times 800 \text{ km}^2$ . Wavenumbers are normalized by each window size. The observed 2D coherences correspond to the three locations described in Fig. 1: (1–3a) N. Cordillera, (1–3b) S-E Cordillera, and (1–3c) Craton. The major axis of the high-coherence ellipse points in the direction of lower  $T_c$ , or  $T_{\min}$ .

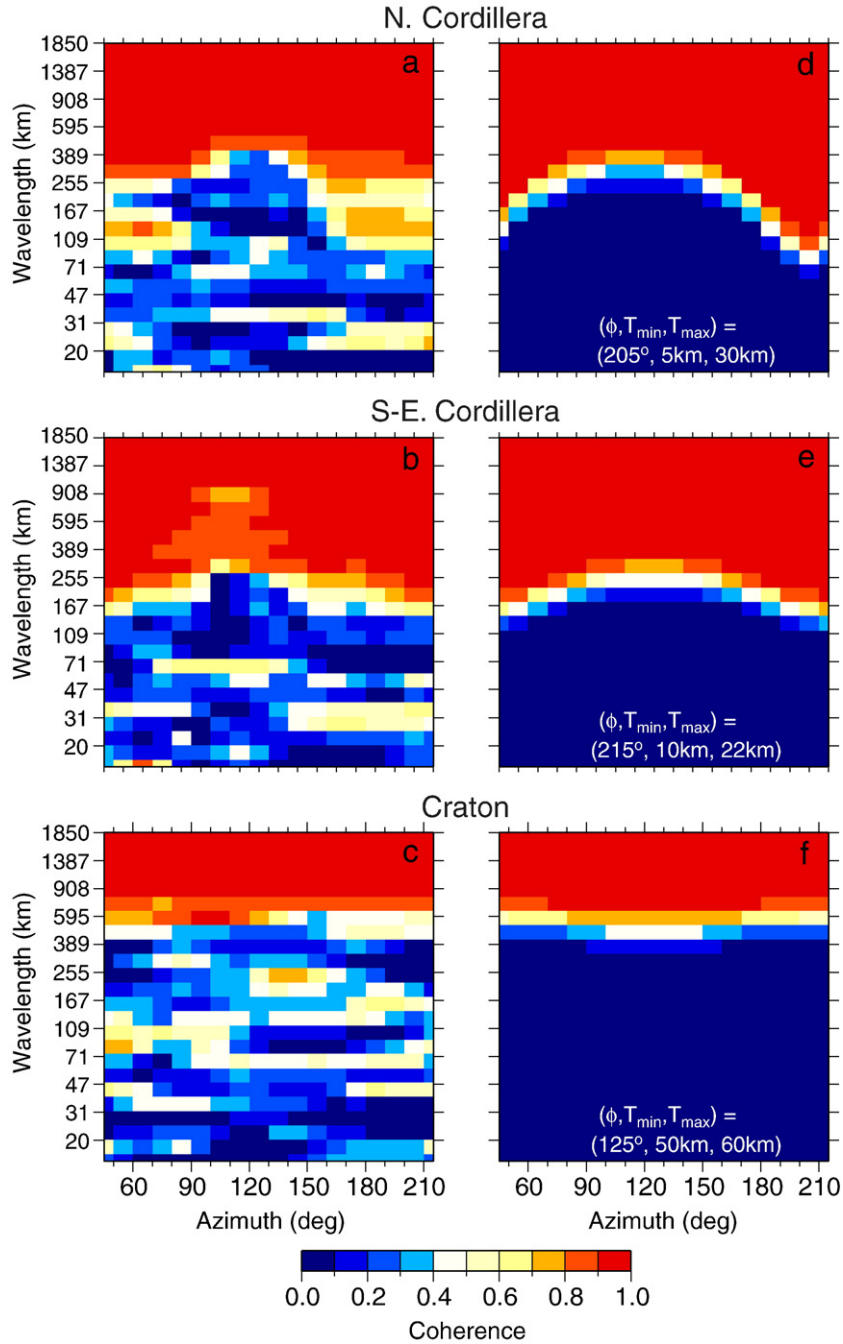


Fig. 5. Anisotropic inversion of  $T_e$  using the wavelet transform method. The coherence is plotted as function of wavelength and azimuth. Observed (a–c) and theoretical (d–f) 2D coherences for the three locations: (a) N. Cordillera, (b) S-E Cordillera, and (c) Craton. Legend in 2D theoretical plots indicates best-fitting parameters of the orthotropic elastic plate. The anisotropy is well developed in the N. Cordillera and in the S-E Cordillera, but almost absent in the Craton.

with the flexure of an elastic plate can be mapped as  $T_e$  and thus lower the  $T_e$  average over the region. The extent to which this short-wavelength anomaly affects the mapping of  $T_e$  is thus controlled by the spatial resolution: in the multitaper estimates, it will dominate the  $T_e$  mapping until a large enough window is able to resolve

the flexural wavelength (c.f. Eq. (1),  $d \sim \lambda_F$ ). This situation is amplified by the fact that our study area is small, and thus only a small number of the largest windows is used. In the wavelet method the deconvolution is performed at each grid point and thus incorporates less information from neighboring grid points. Because this



high coherence is observed at short wavelengths, the mapping of the wavelet estimates of  $T_e$  is less affected by the spurious coherence.

Although a more careful picking of  $T_e$  estimates according to the  $T_e$  sensitivity for each window size (see for e.g. Flück et al., 2003; Pérez-Gussinyé et al., 2004) could perhaps erase this low- $T_e$  anomaly, we prefer to avoid making any a priori assumption about the underlying  $T_e$  structure because this introduces an additional observational bias. Alternatively, Pérez-Gussinyé et al. (2007) calculated multitaper  $T_e$  estimates using three window sizes and produced three maps of  $T_e$  in South America that compared favorably with the wavelet method in the same region (Tassara et al., 2007). Another approach is to weight the misfit by the inverse of wavenumber, as was done in Kirby and Swain (2006), Swain and Kirby (2006) and Tassara et al. (2007). This filtering procedure downweights the contribution of the high coherence at small wavenumbers, effectively erasing the low- $T_e$  anomaly, at the cost of spatial resolution (Kirby and Swain, 2006; Pérez-Gussinyé et al., 2007). We note that the wavelet map of  $T_e$  also shows an intriguing low- $T_e$  region at the north-east corner of the study area, with a lesser spatial extent. Such low- $T_e$  estimates due to short-wavelength coherence is also found elsewhere in the Canadian Shield (Audet and Mareschal, 2004, 2007). The origin of those features is beyond the scope of this study.

We suggest that a more thorough comparison between the wavelet and multitaper methods applied to  $T_e$  is

needed in order to isolate the contribution of the methods themselves to the differences observed.

### 3.2. Anisotropic $T_e$

Fig. 4 shows example results for the anisotropic coherence calculated with the multitaper method at the same three locations as those in Fig. 1. Also shown are best-fitting 2D coherences using analytical solutions of the orthotropic elastic plate (Kirby and Swain, 2006; Audet and Mareschal, 2007). In a 2D wavenumber plot ( $k_x, k_y$ ) of coherence, anisotropic  $T_e$  typically produces an elliptical shape of high coherence, whereas isotropic  $T_e$  appears as a circular region of high coherence. Fig. 4 indicates that the anisotropy is well-developed in the N. Cordillera as the results for the three window sizes are consistent. In the S-E Cordillera the coherence is quasi isotropic except for the estimate obtained with the largest window. The Craton estimates show an absence of coherence at the longest wavelengths as in the 1D case, indicating that still larger windows are necessary to resolve  $T_e$  and the anisotropy in this region.

The wavelet results (Fig. 5) are presented in 2D as wavelength–angle plots. The signature of anisotropic  $T_e$  is then characterized by a  $180^\circ$  periodic variation of high coherence, whereas the signature of isotropic  $T_e$  is a flat line. The wavelet results agree with the multitaper results and show that the anisotropy is well developed in the N. Cordillera and in the S-E Cordillera, but almost absent in

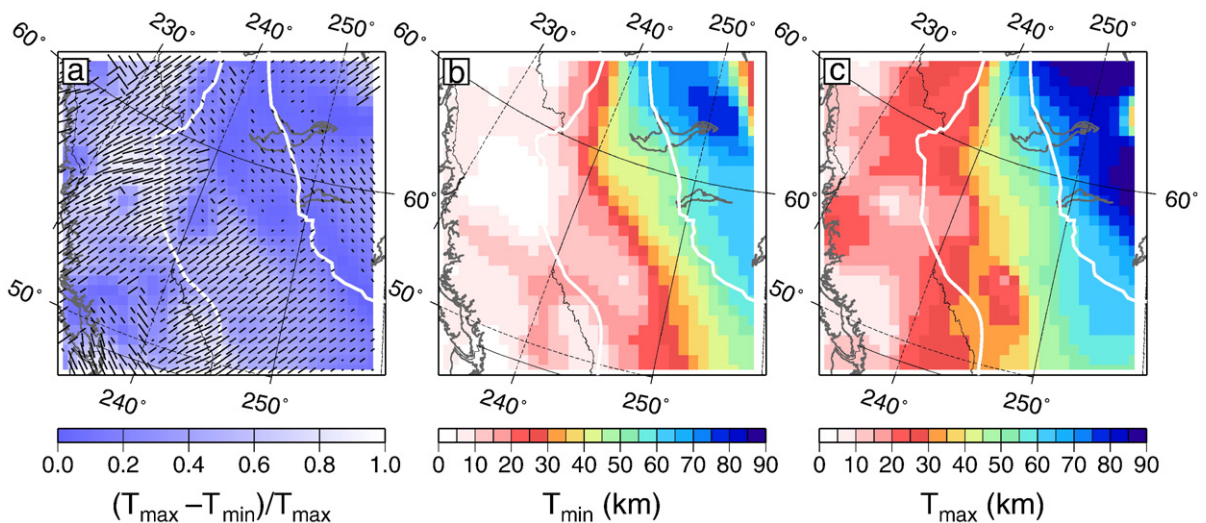


Fig. 6. Anisotropic  $T_e$  structure of western Canada from the wavelet transform method. The 2D coherence is inverted using the thin orthotropic plate model, i.e. having different rigidities in two perpendicular directions, for three parameters: the minimum (b) and maximum (c) values of  $T_e$ , and  $\phi$  the orientation of the weak direction calculated anti-clockwise from the  $x$ -axis (a). The weak direction of mechanical anisotropy in (a) is plotted as thin solid black bars superposed on a color scale map of the anisotropic magnitude. The patterns of  $T_{\min}$  and  $T_{\max}$  closely mimic the isotropic  $T_e$  structure of Fig. 3. In particular, the maximum gradient occurs at the same location, and accompanies a change in both the magnitude and orientation of the weak direction.

the Craton. Maps of  $T_e$  anisotropy using the multitaper method show considerable scatter with the major trends described above, and we choose not to interpret them.

The resulting map of the anisotropic inversion of  $T_e$  using the wavelet method is shown in Fig. 6. The magnitude of  $T_e$  anisotropy is given by the ratio  $(T_{\max} - T_{\min})/T_{\max}$ .  $T_e$  anisotropy is maximized in the Cordillera and across the Interior Plains where  $T_e < 30$  km, closely mimicking the isotropic  $T_e$  pattern. The mechanical weak (i.e. low rigidity) direction is dominantly SW–NE in this region, approximately perpendicular to the main belts of the Cordillera and parallel to the direction of Cascadia subduction. East of  $T_e = 30$  km contour, the  $T_e$  anisotropy progressively decreases in magnitude. In addition, the trend of the weak direction,  $\phi$ , rotates to a SE–NW direction in the Craton and in the northernmost part of the Interior Plains. We note also that the maps of  $T_{\min}$  and  $T_{\max}$  follow closely the isotropic  $T_e$  structure of Fig. 3. In particular, the maximum gradient occurs at the same location.

### 3.3. Geophysical correlations

In Fig. 7a we plot the location of the highest  $T_e$  gradient using the wavelet results, along with the location of earthquake epicenters for all events with magnitude larger than  $M=3$  that occurred since 1979. On the map is also shown a  $150 \times 1800$  km<sup>2</sup> corridor trending SW–NE

within which  $T_e$ ,  $T_e$  gradient ( $|\nabla T_e|$ ), and crustal thickness ( $T_c$ ) were extracted and averaged, and plotted in Fig. 7b. Fig. 7c shows  $T_e$  with the percentage of seismicity and heat flow values along the same profile. The highest  $T_e$  gradient is found in the Interior Plains, 100 to 300 km west of the largest concentration of seismicity, and also where  $T_e < 30$  km. The position and magnitude of the  $T_e$  gradient also broadly correlate with a similar (i.e. factor of about 2) eastward decrease in vertical heat flux (Hyndman and Lewis, 1999), consistent with inferences from xenolith thermobarometry and seismic data (Currie and Hyndman, 2006). The  $T_e$  gradient corresponds also to a transition in crustal thickness from  $\sim 30$  km in the Cordillera to  $>40$  km in the Craton (Perry et al., 2002), and with a gradient of low to high S-wave seismic velocity anomalies imaged by seismic tomography (Frederiksen et al., 2001).

In Fig. 8a we plot the  $T_e$  weak directions along with seismic and magnetotelluric measurements of crustal and upper mantle anisotropy and indicators for crustal stresses. Fig. 8b shows the magnitude of the  $T_e$  anisotropy with averages of  $T_{\min}$  and  $T_{\max}$  along the same profile as Fig. 7. In the southern Cordillera and across the Interior Plains the fast axis of seismic anisotropy, as measured from SKS splitting data, show coherent fast polarizations in the SW–NE direction (Shragge et al., 2002; Currie et al., 2004). The geoelectric strikes align in the same direction as the SKS data (Boerner et al., 1999; Ledo and Jones, 2001). Both

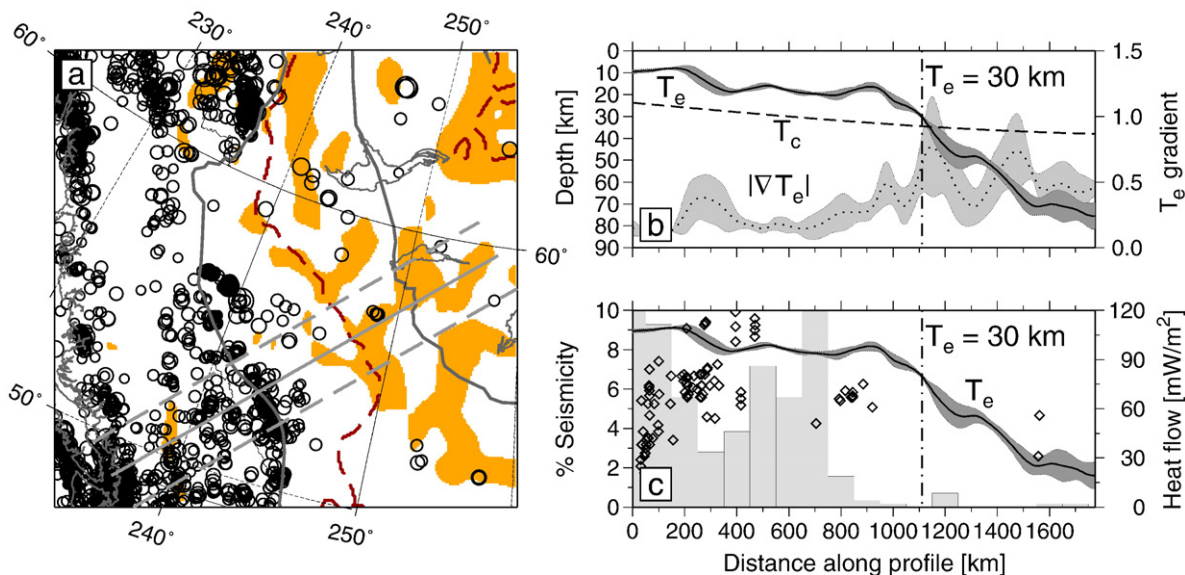


Fig. 7. Correlations between the  $T_e$  structure and geophysical data. In (a) the seismicity (with magnitude  $>3$ ) of western Canada, represented by black circles at earthquake epicenters recorded between 1979 and 2006, is plotted against the location of the maximum gradient of  $T_e$  shown in orange. Thick grey lines are the province boundaries. Dashed dark red line is the 30 km contour which roughly follows the maximum gradient limit. (b) shows the average of  $T_e$ ,  $T_c$  gradient, and  $T_c$  calculated within the corridor delimited by the thick gray dashed lines in (a), and projected along the profile shown by the thick gray line. In (c) the  $T_e$  is plotted against the seismicity (gray bins) and heat flow values (diamonds) extracted within the same corridor and projected along the profile. The west–east decrease in seismicity correlates with the location of the  $T_e$  gradient, where  $T_e \sim T_c \sim 30$  km, and where heat flow decreases by a factor of 2.

anisotropy indicators align with the  $T_e$  weak directions and with the maximum horizontal compressive stress directions. This striking uniform pattern of anisotropy persists over a wide area to about  $57^\circ$  latitude, and correlates with a change in  $T_e$  from  $T_e < T_c$  to  $T_e > T_c$ . This also corresponds to the boundary defined by the largest  $T_e$  gradient, where  $T_e \sim 30$  km, and where the  $T_e$  anisotropy changes in both amplitude and direction.

In order to quantitatively compare the anisotropy datasets, we resampled the seismic, magnetotelluric and

stress data onto the coarse  $T_e$  anisotropy grid. Fig. 9 shows histograms of the difference in angle between the  $T_e$  weak directions and the seismic, magnetotelluric, and stress directions, along with a histogram of percent alignment to within  $15^\circ$  and  $22.5^\circ$  (Simons and van der Hilst, 2003). Stress and magnetotelluric data show well-defined Gaussian curves centered on  $\sim 10^\circ$  to  $20^\circ$  difference with  $T_e$  anisotropy (Fig. 9b,c), and the alignments are well above the  $15^\circ$  and  $22.5^\circ$  significance levels (Fig. 9d). The angle differences between  $T_e$  weak axes and seismic fast axes

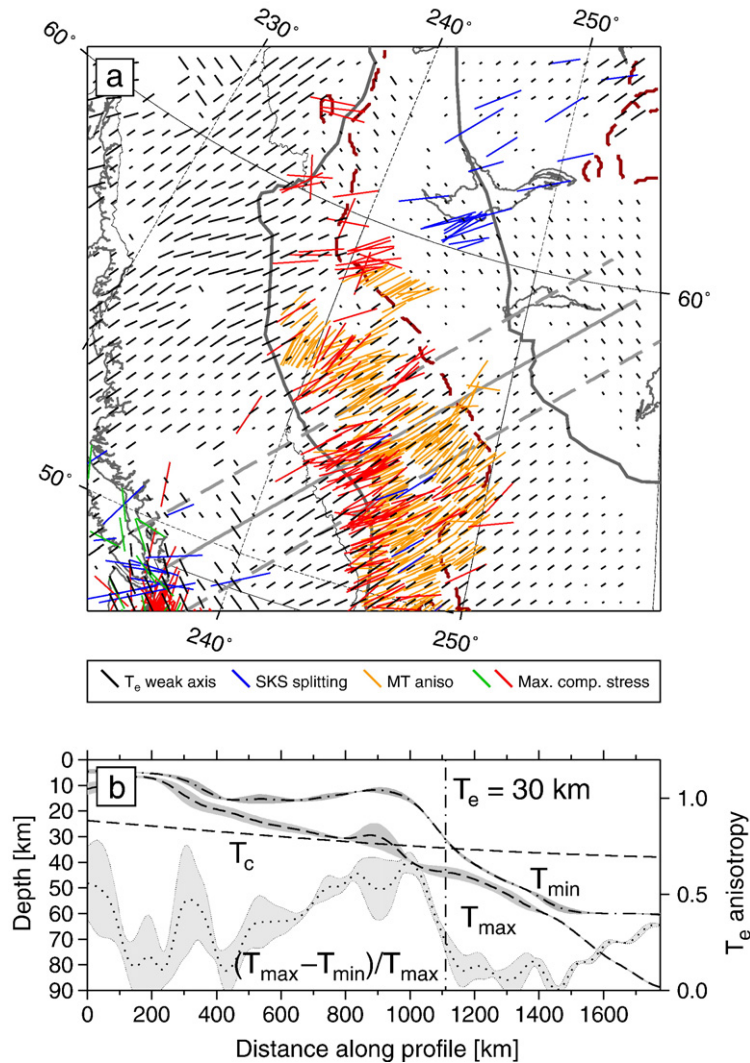


Fig. 8. Anisotropy correlations in western Canada. In (a) the mechanical weak axes (black bars) are plotted along with seismic (SKS splitting — blue bars (Shragge et al., 2002; Eaton et al., 2004; Currie et al., 2004), and electrical (geoelectric strikes — orange bars (Boerner et al., 1999)) anisotropy data. Green and red bars are maximum compressive horizontal stress directions inferred from shear-wave splitting above local earthquakes in the Cascadia forearc (Currie et al., 2001) and borehole breakouts, respectively. Dashed dark red line is the  $T_e = 30$  km contour. (b) shows the average of  $T_{\min}$ ,  $T_{\max}$ , and the magnitude of  $T_e$  anisotropy calculated within the corridor and projected along the profile as in Fig. 7b,c. The boundary defined by  $T_e \sim 30$  km correlates with a decrease in  $T_e$  anisotropy. In the southern Cordillera and across the Interior Plains all indicators align in the direction of plate motion and subduction of Juan de Fuca beneath North America, suggesting a stress control on the deformation of western Canada. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)



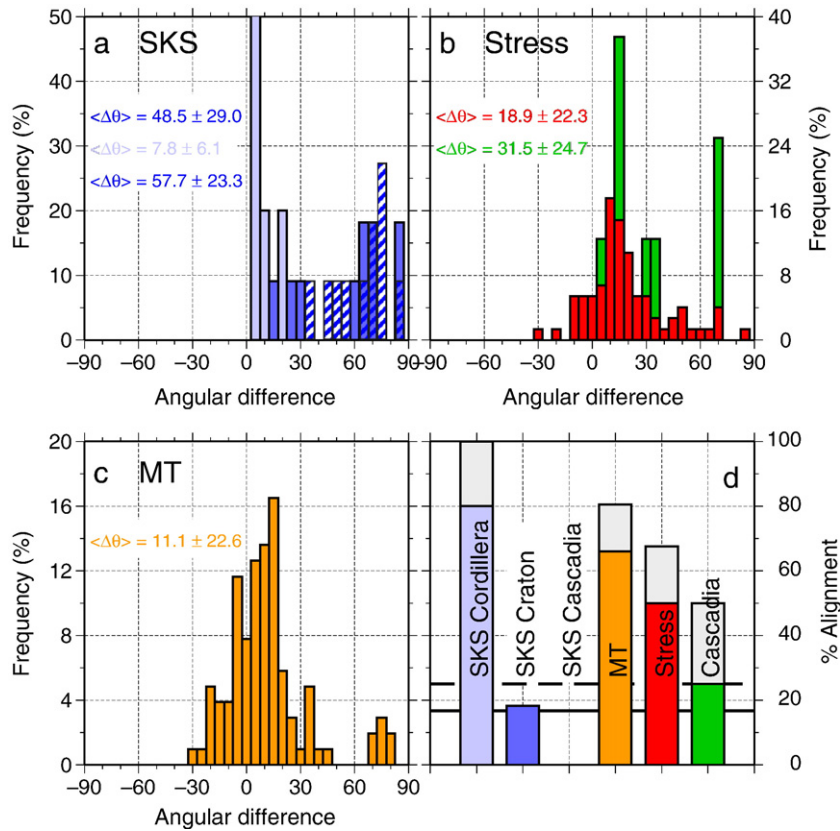


Fig. 9. Statistics of anisotropy to test whether the observed alignment between  $T_c$  weak directions and other anisotropy indicators is significant. In (a), (b), and (c) the histograms show the angular difference between the  $T_c$  weak axes and seismic fast axes, maximum horizontal compressive stress directions, and geoelectric strikes respectively. The seismic anisotropy in (a) is further divided into three regions corresponding to the Cordillera (light blue), the Craton (dark blue), and the Cascadia backarc (hatched dark blue). Shown in (d) are the percentage of alignment to within 15° (colored bins), and to within 22.5° (light gray). Continuous and dashed black lines indicate the levels at which randomly distributed alignment should fall within 15° and 22.5°. High percentage of alignment suggests a causal link between the observables.

show a quasibimodal distribution centered on  $\sim 10^\circ$  and  $\sim 75^\circ$  (Fig. 9a). When binned into three distinct regional clusters (Cascadia backarc, Cordilleran Front, and Craton), the alignment between  $T_c$  weak axes and the seismic fast axes in the Cordilleran portion emerges (Fig. 9a,d, light blue). The Cascadia and Craton regions show angle differences larger than  $45^\circ$  with a marked proportion of data towards orthogonality. However more seismic data are required to assess the general trends observed.

#### 4. Discussion

##### 4.1. $T_e$ , $T_c$ , and heat flow

The relationship between  $T_e$  and  $T_c$  requires some discussion because it provides insight into the factors that influence  $T_e$  most strongly (Burov and Diament, 1995; Lowry and Smith, 1995). That  $T_e < T_c$  in the

Cordillera suggests that the average elastic properties of this region are governed, in part, by the composition and constitution of crustal rocks. In contrast, the elastic properties of the Craton, where  $T_e > T_c$ , must involve a component of the lithospheric mantle, although the nature and extent of the mechanical coupling of the crust to the underlying lithosphere is unknown. In principle the vertical structure of the lithosphere and its influence on plate rigidity is determined, in part, locally and regionally by geology and may be complex. However, the eastward increase in  $T_e$  is significantly greater than that which is expected if plate rigidity is related to changes in  $T_c$  alone (i.e.  $D$  is not proportional to  $T_c^3$ ). Indeed, the roughly factor of 2 variation in  $T_e$  is better explained by the similar variations in heat flux that will scale approximately as  $1/T_e$  if  $T_e$  is proportional to the lithospheric thickness (Maggi et al., 2000). This result suggests that although a geologically complex region,

$T_e$  is predominantly governed by temperature in western Canada, as speculated in previous studies (Hyndman and Lewis, 1999; Flück et al., 2003).

#### 4.2. Anisotropy and stress: a primer

Seismic anisotropy refers to variations of seismic wavespeeds along different directions of propagation or polarization (Silver, 1996; Savage, 1999). The most popular method for investigating seismic anisotropy is the splitting (or birefringence) of shear-waves travelling through the mantle. In an anisotropic mantle with a horizontal axis of symmetry, the two perpendicular shear-wave polarizations will split into a fast and a slow component. The time difference between the two phases provides an estimate of the magnitude of the anisotropy, whereas the fast polarization azimuth measures the direction of the symmetry axis. Time delays and azimuths give an indication of elastic anisotropy within the lithosphere, and can thus image deformation of the rocks in the Earth's mantle.

Under the continents, the seismic anisotropy is attributed either to frozen fabric in the lithospheric mantle (Silver, 1996), or to present-day sublithospheric mantle convection (Vinnik et al., 1992). In western Canada, almost all the seismic anisotropy data are measured by the splitting of SKS phases and are interpreted to result from shear-induced lattice-preferred orientation (LPO) of olivine in the upper mantle due to viscous flow (Bank et al., 2000; Shragge et al., 2002; Currie et al., 2004). Despite the excellent lateral resolution afforded by this method, these measurements are hampered by a poor depth resolution and/or the presence of complex anisotropic layering (Park and Levin, 2002), hindering a robust estimation of the source of the anisotropy.

Electrical anisotropy is seen by the azimuthal dependence of the phase difference between the two orthogonal horizontal components (transverse electric — TE — and transverse magnetic — TM) of the time-dependent electro-magnetic (EM) fields of magnetotelluric (MT) measurements (Boerner et al., 1999; Eaton et al., 2004; Jones, 2006). The magnitude of the electrical anisotropy is generally of a few orders of magnitude, rather than a few percents as in shear-wave anisotropy, and hence rules out the possibility of an intrinsic dry crystal or grain electrical anisotropy. Electrical anisotropy may be generated by macroscopic, graphitized (resistive) shear zones within the lithosphere that mark past tectonic events (Mareschal et al., 1995), by grain-scale anisotropy of strain-induced LPO of wet olivine crystals oriented by present-day plate motion or mantle flow (Simpson, 2001),

or by enhanced fluid flow in the crust and upper mantle due for example to water being incorporated into the subduction zone (Ledo and Jones, 2001; Soyer and Unsworth, 2006) or originating from a meteoric source.

MT strike directions at a particular period represent an integrative effect of the electrical structure at a broad depth range related to the diffusion of the EM fields into a conductor. However the penetration depth of the TE field can differ from that of the TM field by tens of kilometers due to strong structural heterogeneity (Jones, 2006). Electrical anisotropy data shown in Fig. 8 show the strike directions at a period of 320 s, which is broadly representative of mid-crustal depths (Boerner et al., 1999). A reliable indicator of the electrical anisotropy magnitude is the phase separation between the impedance estimates for the two transverse modes that is consistent on a regional scale. In the Interior Plains the phase difference is maximum south of 57°, and diminishes to the north and southeast (Boerner et al., 1999). Electrical anisotropy in this region requires a hydrothermal alteration event most likely related to the tectonic assembly of Laurentia circa 1850 Ma (Boerner et al., 1999). Note that the high correlation between present-day stress and MT anisotropy rather suggests a causal link and we provide an alternative explanation for the MT anisotropy in the next section.

Seismic and electrical anisotropies mostly sample upper mantle/mid-crustal materials, but although they do not measure the same physical properties, they may be measuring the response of the same causative effect. The anisotropy in  $T_e$  provides an integrated measure of the rheology of the lithosphere at crustal and upper mantle depths and thus it fills the gap between these anisotropy measurements and surface geology features (Lowry and Smith, 1995; Simons and van der Hilst, 2003).

A number of mechanisms can induce mechanical anisotropy of the lithosphere. The azimuthal dependence of the coherence between gravity anomalies and topography indicates that flexural compensation is facilitated in the direction perpendicular to the direction that has accumulated the most deformation per unit of topographic loading, which is accommodated by folding, faulting, or buckling of the crust (i.e. the weak axis is perpendicular to strike) (Simons and van der Hilst, 2003). If the preserved gravity structure reflects the current state of stress of the lithosphere due for example to plate convergence, then the weak direction aligns in the direction of maximum compressive stress (Lowry and Smith, 1995), and that of shear strain-induced seismic anisotropy if flow is parallel to convergence. High amplitude  $T_e$  anisotropy thus reflects



the preserved strain field that is likely to be related to crustal stresses and associated brittle processes (e.g. faulting, seismicity) at active convergent margins.

#### 4.3. Conceptual model of deformation

The diverse geophysical correlations of Figs. 7 and 8, and the discussion in Section 4.2, suggest a simple conceptual model for the current state of stress and the associated brittle deformation in western Canada (Fig. 10). The alignment of the seismic anisotropy data with crustal stress indicators suggests that elastic stresses, expressed as both flexurally-supported topography, and brittle failure, indicated by earthquakes, arise in response to driving plate boundary forces and retarding mantle tractions related to Cascadia subduction and associated mantle flow. The sharp and nearly factor of 10 increase in the thickness of the elastic lithosphere from the Cordillera to the Craton is interpreted to cause bending related to a compressional component of the stress field to be concentrated a couple of hundred kilometers west of the  $T_e$  gradient. The location of this stress concentration is consistent with expectations from simple calculations of the flexural characteristics of beams and plates of variable rigidity. Elastic bending stresses scale as  $(E/(1-\nu^2)) (T_e/R)$ , where  $\nu$  and  $R$  are Poisson's ratio and the radius of curvature of the deformation, and will exceed the  $\sim 30$  MPa yield strength of the crust for even very small vertical deflections of the cordilleran lithosphere (i.e. for  $R < O(10^4)$  km, say).

That seismicity and mechanical weakening occurs where bending stresses are maximized is thus not surprising. If the bending is simple (approximately cylindrical, Fig. 10) failure is expected to occur in tension

(leading to normal faults) and compression (leading to reverse faults) in the upper and lower halves of the elastic lithosphere, respectively. Results from geologic mapping (Carr et al., 1988) and regional GPS studies are consistent with this picture and, moreover, indicate that significant upper crustal extension and normal faulting has occurred in this region over an extended period of time (Carr et al., 1988). It is worth noting that our conceptual elastic model predicts the location of failure, regardless of the amount of finite-amplitude deformation produced thereafter, which involves no elasticity.

The enhanced west–east electrical conductivity is sufficiently large to require a fluid phase (Boerner et al., 1999; Ledo and Jones, 2001; Soyer and Unsworth, 2006), where the fluids may come either from the mantle or meteoric sources. If this electrical anisotropy is explained by a conductivity that is enhanced by charge being carried by the flow of crustal fluids it is reasonable to speculate that mechanical failure of the rocks in this region leads also to fracture permeability, with enhanced flow along pre-existing grain boundaries, and that this mechanism dominates over macroscopic fluid flow along faults, which would create a NW–SE trending MT anisotropy.

Interestingly, the maximum compressive direction of crustal stress indicators in the Cascadia forearc, inferred from the splitting of direct shear-waves generated by local earthquakes (Currie et al., 2001) and in-situ measurements, are oriented in a NW–SE direction (Fig. 7b). These observations are in agreement with the forearc sliver model of Wang (1996) who predicts large arc-parallel compressive stresses due to oblique subduction. The anisotropy in  $T_e$  in this region is in agreement with the predictions and observations of crustal stresses in the Cascadia forearc.

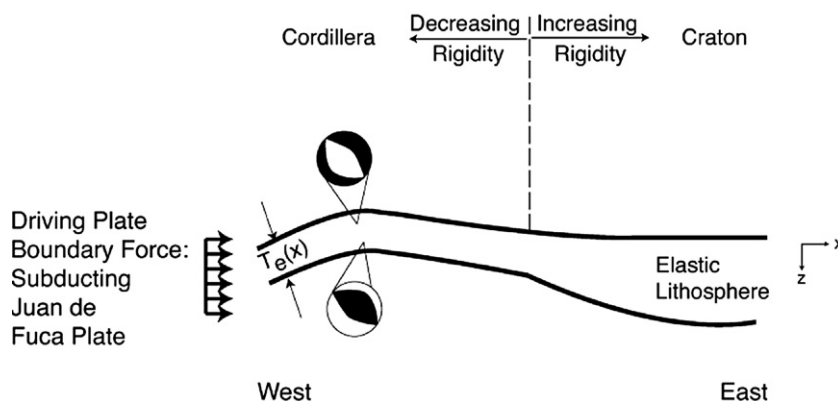


Fig. 10. Cartoon showing a geodynamic interpretation of the elastic thickness results. The driving forces for lithospheric deformation at the convergent margin of western Canada are due to the subduction of the Juan de Fuca plate beneath North America. The elastic plate flexes in response to the loads applied at the plate boundary, and the stresses concentrate where rigidity is lowest, west of the maximum gradient of  $T_e$ . Brittle failure and seismicity occur in the upper and lower halves of the plate as a result of displacement along normal and reverse faults, respectively. Note that the amplitude of the flexure is significantly exaggerated (to finite-amplitude) to highlight the underlying mechanics of the flexure and failure processes.

The northern Cordillera represents a remarkably tectonically and seismically active region where the collision of the Yakutat Block drives the deformation at least 1000 km farther inland (Hyndman et al., 2005). Our limited coverage of this region hampers a more quantitative comparison of the mechanical controls on the deformation, although the very steep gradient in  $T_e$  north of 60° suggests that the same mechanisms operate in this region (see Fig. 7). More  $T_e$  data north of 60° latitude along with constraints from other geophysical observables are needed to verify the validity of our mechanical model in the northern Cordillera.

The conceptual model explains the stress-induced deformation where the lithosphere is weakest and where deformation is most likely controlled by the rheology of the crust, but fails to explain all the features observed on the anisotropy correlation map (Fig. 8), notably in the Craton. In this region  $T_e$  is larger than  $T_c$  but much lower than the ~300 km thick lithosphere, suggesting that at least part of the lithospheric mantle contributes to the rigidity. The fact that seismic fast axes align in the direction of absolute plate motion indicates that the anisotropy is consistent with shear-induced LPO of olivine in the upper mantle due to viscous flow (Bank et al., 2000). Because the very rigid Craton largely escapes deformation and is unaffected by present-day stress levels within the lithosphere, the  $T_e$  anisotropy therein most likely reflects the fossil strain field from past tectonic events and may not correlate with the deformation associated with the present-day absolute plate motion at the base of the lithosphere (Simons and van der Hilst, 2003). On the other hand, if the seismic anisotropy were due to frozen fabric within the lithosphere, the seismic fast axes should anti-correlate with the  $T_e$  weak directions (Simons and van der Hilst, 2003). The absence of constraints from other geophysical observables renders this hypothesis difficult to assert in a testable way.

## 5. Conclusion

The estimation of the spatial variations of the elastic thickness is a complex spatio-spectral problem because the elastic response of the plate to loading is dominated by features with wavelengths much larger than  $T_e$ . To address this issue, we use the multitaper and wavelet transform methods to obtain detailed maps of  $T_e$  and its anisotropy in western Canada. Our results are compared to relevant data sets and suggest that under the current tectonic stress regime the locations of brittle fracturing of crustal rocks, indicated by seismicity, mechanical anisotropy, and enhanced electrical conductivity (i.e. fracture permeability), are governed by the detailed spatial

variations in plate rigidity. Whether or not this simple conceptual model is validated by more thorough geodynamic modelling of the deformation of western Canada, our work indicates that an accurate determination of the spatial variations in  $T_e$  is fundamental to understanding the modern processes governing lithospheric deformation at active continental margins in general.

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